

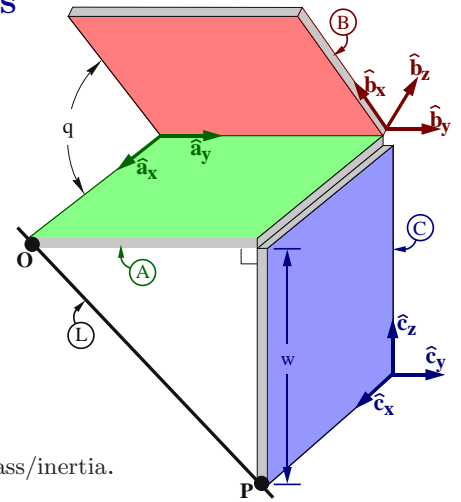
### 7.3 Mass, mass center, and inertia calculations

The figure to the right shows three identical uniform hinge-connected plates  $A$ ,  $B$ , and  $C$ .

Right-handed sets of mutually perpendicular unit vectors  $\hat{\mathbf{a}}_i$ ,  $\hat{\mathbf{b}}_i$ , and  $\hat{\mathbf{c}}_i$  ( $i = x, y, z$ ) are fixed in  $A$ ,  $B$ , and  $C$ , respectively, with  $\hat{\mathbf{a}}_y = \hat{\mathbf{b}}_y = \hat{\mathbf{c}}_y$  parallel to the hinge connecting  $A$  and  $B$ .

The plates are thin and square and have dimension  $w = 1$  meter and mass  $m = 12$  kg.

Points  $O$  and  $P$  mark corners of  $A$  and  $C$  and the angle  $q$  characterizes  $B$ 's orientation in  $A$ .



Note: Problem solution at [www.MotionGenesis.com](http://www.MotionGenesis.com)  $\Rightarrow$  [Get Started](#)  $\Rightarrow$  Plate mass/inertia.

- Find the distance between line  $\overline{OP}$  and the center of mass  $S_{cm}$  of the system formed by  $A$ ,  $B$ ,  $C$ .

**Result:**

$$\text{Distance} = 0.1178511 \sqrt{42 + \cos^2(q) + 6 \sin(q) - 16 \cos(q)}$$

- For  $q = 90^\circ$ , find  $\lambda_i$  ( $i=1,2,3$ ), the system's principal moments of inertia about  $S_{cm}$ . Next, find the angle between  $\hat{\mathbf{a}}_y$  and the principal axis associated with this system's **minimum** moment of inertia.

**Result:**

$$\lambda_1 = 5 \text{ kg m}^2 \quad \lambda_2 = 13 \text{ kg m}^2 \quad \lambda_3 = 14 \text{ kg m}^2 \quad \text{Angle} = 65.90516^\circ$$

- The system's radius of gyration about line  $\overline{OP}$  is a measure of how far the mass distribution is from line  $\overline{OP}$  and is defined as  $\sqrt{I/m}$  where  $I$  is the system's moment of inertia about  $\overline{OP}$  and  $m$  is the system's mass. Using **physical intuition**, estimate the values of  $q$  that produce the smallest and largest radii of gyration about line  $\overline{OP}$  and provide a reason for choosing these values.

**Result:**  $q_{\text{small}} \approx 340^\circ$   $q_{\text{large}} \approx 160^\circ$  ( $0 \leq q \leq 360^\circ$ )

**Reason:** These values minimize or maximize the distance from line  $OP$  to  $B$ 's mass center.

Plot the system's mass center distance from line  $\overline{OP}$  and the system's radius of gyration about line  $\overline{OP}$  for  $0 \leq q \leq 360^\circ$ . Determine the minimum/maximum distance and radius of gyration

- and associated values of  $q$ .

	Minimum Value	$q$	Maximum Value	$q$
Distance	0.598 m	337°	0.913 m	161°
Gyration	0.696 m	340°	1.084 m	169°

