

16.1 ♣ Two types of forces in a *free-body diagram (FBD)* (Section 18.6).

From an engineering/FBD perspective, the two types of forces are contact and distance.

16.2 ♣ What is 1 Newton and 1 lb<sub>f</sub>? (Section 21.1).

1 Newton is defined as (circle all that apply)	<input checked="" type="checkbox"/> $1 \frac{\text{kg m}}{\text{s}^2}$	<input type="checkbox"/> $9.81 \frac{\text{kg m}}{\text{s}^2}$	<input type="checkbox"/> $32.2 \frac{\text{kg m}}{\text{s}^2}$	<input type="checkbox"/> None of these
1 lb <sub>f</sub> is defined as or approximately equal to (circle all that apply)	<input type="checkbox"/> $1 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$	<input checked="" type="checkbox"/> $1 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$	<input type="checkbox"/> $1 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$	
	<input type="checkbox"/> $9.81 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$	<input type="checkbox"/> $9.81 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$	<input type="checkbox"/> $9.81 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$	
	<input type="checkbox"/> $32.2 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$	<input type="checkbox"/> $32.2 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$	<input checked="" type="checkbox"/> $32.2 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$	

Using the exact Section 21.1 NIST conversion factor for lbm to kg and the exact conversion factor 1 inch ≜ 2.54 cm, show how to calculate the conversion factor for lbf to Newton.

**Result**  
 $1 \text{ lbf} \approx \frac{32.2 \text{ lb}_m \text{ ft}}{\text{s}^2} * \frac{0.45359237 \text{ kg}}{1 \text{ lb}_m} * \frac{12 \text{ inch}}{1 \text{ ft}} * \frac{2.54 \text{ cm}}{1 \text{ inch}} * \frac{1 \text{ m}}{100 \text{ cm}} * \frac{1 \text{ N}}{1 \text{ kg m/s}^2} \approx 4.45 \text{ N}$

16.3 ♣ Force concepts (Section 18.3).

A force is a well-defined quantity:	True/ <input checked="" type="checkbox"/> False
The resultant of a set of forces is a force.	True/ <input checked="" type="checkbox"/> False
In the SI (metric) system, the units of force are:	<u>Newtons</u>
In the SI (metric) system, the units of impulse are:	<u>Newton * sec</u>
$\vec{F} = m \vec{a}$ is violated if a non-zero forces exists without the presence of a massive object	<input checked="" type="checkbox"/> True/ <input type="checkbox"/> False
$\vec{F} = m \vec{a}$ is violated if mass exists without the presence of force	True/ <input checked="" type="checkbox"/> False

16.4 ♣ Law of action/reaction (Section 18.1).

Circle the forces that obey the *law of action/reaction*. Explain why each pair obeys/disobeys.

Forces have equal magnitude, opposite directions, and directed towards each other.

Force magnitudes are *unequal*.

Forces are *not* directed along line  $\overline{PQ}$  (different lines of action).

16.5 ♣ Coulomb's friction law (Section 21.6).

The range for Coulomb's *coefficient of static friction* is always  $0 \leq \mu_s \leq 1$ . True/ False.

Coulomb's friction law is exact/accurate (< 1% error)/ approximate/completely wrong.

16.6 ♣ Force and mass concepts (Section 21.1).

The center of mass and center of gravity may be different points.	<input checked="" type="checkbox"/> True/ <input type="checkbox"/> False
The center of gravity of a rigid body always exists.	True/ <input checked="" type="checkbox"/> False

**16.7 ♣ Convert U.S. units of psi to SI units of Pascals and estimate stress (Section 21.1).**

Use each conversion factors (number) below at least once (and others you should know) to convert units of 1 inch to **x** meters, 1 lbf (pound-force) to **y** Newtons, and 1 psi ( $\frac{\text{lbf}}{\text{inch}^2}$ ) to **z** Pascals ( $\frac{\text{N}}{\text{m}^2}$ ). Express your results for **z** in terms of the intermediate conversion factors **x** and **y**.

$$1 \text{ inch} \triangleq 2.54 \text{ cm} \qquad 1 \text{ kg} \approx 2.2 \text{ lbm} \qquad 1 \text{ g}_{\text{Earth}} \approx 32.2 \frac{\text{ft}}{\text{s}^2}$$

Conversion Equation (with numbers and units) for calculating result.

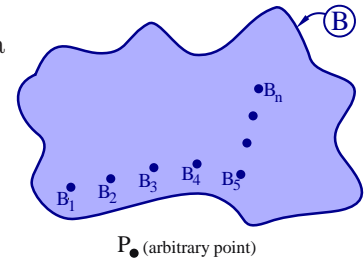
1 in = <b>x</b> m	<b>x</b> = 1 in * $\frac{2.54 \text{ cm}}{1 \text{ in}}$ * $\frac{1 \text{ m}}{100 \text{ cm}}$ $\approx 0.0254$	<b>Example of how to do units conversions</b>
1 lbf = <b>y</b> N	<b>y</b> = 1 lbf * $\frac{1 \text{ lbm} * 32.2 \frac{\text{ft}}{\text{s}^2}}{1 \text{ lbf}}$ * $\frac{1 \text{ kg}}{2.2 \text{ lbm}}$ * $\frac{12 \text{ in}}{1 \text{ ft}}$ * $\frac{2.54 \text{ cm}}{1 \text{ in}}$ * $\frac{1 \text{ m}}{100 \text{ cm}}$ * $\frac{1 \text{ N}}{1 \text{ kg} \frac{\text{m}}{\text{s}^2}}$ $\approx 4.45$	
1 psi = <b>z</b> Pa	<b>z</b> = $\frac{1 \text{ lbf}}{1 \text{ in}^2}$ * $\frac{\text{y N}}{\text{lbf}}$ * $(\frac{1 \text{ in}}{\text{x m}})^2$ * $\frac{1 \text{ Pa}}{1 \text{ N/m}^2}$ $\approx 6894.757$	<b>Express z in terms of x and y</b>

Engineering skill: Estimate/approximate order-of-magnitudes for mass, force, and stress.

Mass of a laptop computer	0.04/0.4/ <u>4</u> /40/400	lbm
Weight of a laptop computer	0.04/0.4/ <u>4</u> /40/400	lbf
Weight of a laptop computer	0.02/0.2/2/ <u>20</u> /200	Newtons
Gage pressure in a bike tire (remember pumping up a bike/car tire?)	0.05/0.5/5/ <u>50</u> /500	psi
Gage pressure in a bike tire	0.03/0.3/3/30/ <u>300</u>	kPa
Stress of a 200 lbf person on one flat sneaker on a wood floor	0.05/0.5/ <u>5</u> /50/500	psi
Stress of a 120 lbf person on one stiletto heel on a wood floor	0.03/0.3/3/30/ <u>300</u>	psi

**16.8 ♣ Forces on an aluminum body (Sections 18.4, 18.2, and 19.4).**

Consider  $6.022 \times 10^{23}$  molecules of aluminum ( $\approx 27$  grams) which define a body  $B$ . The quantities under investigation (and related moments) are:



- $\vec{F}^B$  the resultant of all forces on  $B$
- $\vec{F}_{\text{internal}}^B$  the resultant of all internal forces in  $B$
- $\vec{F}_{\text{external}}^B$  the resultant of all external forces on  $B$
- $\vec{F}^{B_1/B_2}$  the force on molecule  $B_1$  from molecule  $B_2$

Condition	Static equilibrium?	Circle the following statements that are always true.			
$B$ is rigid	Yes	$\vec{F}^B = \vec{0}$	$\vec{F}_{\text{internal}}^B = \vec{0}$	$\vec{F}_{\text{external}}^B = \vec{0}$	$\vec{F}^{B_1/B_2} = \vec{0}$
		$\vec{M}^{B/P} = \vec{0}$	$\vec{M}_{\text{internal}}^{B/P} = \vec{0}$	$\vec{M}_{\text{external}}^{B/P} = \vec{0}$	$\vec{M}^{\vec{F}^{B_2/B_1}/P} = \vec{0}$
$B$ is flexible (a thin ruler)	Yes	$\vec{F}^B = \vec{0}$	$\vec{F}_{\text{internal}}^B = \vec{0}$	$\vec{F}_{\text{external}}^B = \vec{0}$	$\vec{F}^{B_1/B_2} = \vec{0}$
		$\vec{M}^{B/P} = \vec{0}$	$\vec{M}_{\text{internal}}^{B/P} = \vec{0}$	$\vec{M}_{\text{external}}^{B/P} = \vec{0}$	$\vec{M}^{\vec{F}^{B_2/B_1}/P} = \vec{0}$
$B$ is rigid	No	$\vec{F}^B = \vec{0}$	$\vec{F}_{\text{internal}}^B = \vec{0}$	$\vec{F}_{\text{external}} = \vec{0}$	$\vec{F}^{B_1/B_2} = \vec{0}$
		$\vec{M}^{B/P} = \vec{0}$	$\vec{M}_{\text{internal}}^{B/P} = \vec{0}$	$\vec{M}_{\text{external}} = \vec{0}$	$\vec{M}^{\vec{F}^{B_2/B_1}/P} = \vec{0}$
$B$ is molten (liquid metal)	No	$\vec{F}^B = \vec{0}$	$\vec{F}_{\text{internal}}^B = \vec{0}$	$\vec{F}_{\text{external}} = \vec{0}$	$\vec{F}^{B_1/B_2} = \vec{0}$
		$\vec{M}^{B/P} = \vec{0}$	$\vec{M}_{\text{internal}}^{B/P} = \vec{0}$	$\vec{M}_{\text{external}} = \vec{0}$	$\vec{M}^{\vec{F}^{B_2/B_1}/P} = \vec{0}$

16.9 ♣ **Measurement accuracies of the Universal Gravitational Constant  $G$**  (Section 21.3).

The gravitational force on a particle  $Q$  of mass  $m^Q$  from a particle  $P$  of mass  $m^P$  can be written in terms of  $Q$ 's position vector from  $P$  as

$$\vec{F}^{Q/P} = \frac{-G m^P m^Q}{|\vec{r}^{Q/P}|^3} \vec{r}^{Q/P} \quad (21.3)$$

What are the dimensions of  $G$  (in terms of mass, length and time) and the SI units of  $G$ ?

**Result:** Dimensions of  $G$ : (in terms of mass, length, time)  $\frac{\text{length}^3}{\text{mass} * \text{time}^2}$  Units of  $G$ : (in terms of  $kg, m, s$ )  $\frac{\text{m}^3}{\text{kg} * \text{s}^2}$

The number of significant digits the first measurement of the “*Universal Gravitational Constant*”  $G$  in 1798 by Cavendish and recent (year 2000<sup>+</sup>) experiments of  $G$  are estimated to be accurate to:

Experiments in 1798	1	<b>2</b>	5	7	infinite
Experiments in 2000 <sup>+</sup>	1	<b>2</b>	5	7	infinite

Note: Section 21.3 discusses experiments involving  $G$ .

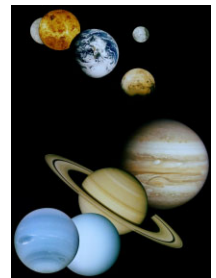
16.10 ♣ **According to Newton’s laws (theories), is the universe static?** (Sections 18.2 and 19.3)

Consider the system  $S$  consisting of all matter, life, forces, etc.<sup>a</sup>

- Newton’s laws dictates the resultant of all forces on  $S$  is  $\vec{0}$ , i.e.,  $\vec{F}^S = \vec{0}$ . **True**/False.
- The moment of all forces on  $S$  about any point  $P$  is  $\vec{0}$ , i.e.,  $\vec{M}^{S/P} = \vec{0}$ . **True**/False.
- Newton’s laws dictates the universe is in **static equilibrium**. **True**/False.
- Newton’s **1<sup>st</sup>/2<sup>nd</sup>/3<sup>rd</sup>** law explains my answer? (circle one)

Why: Since all forces are **inside** the system and the law of action/reaction states each force has an equal and opposite force, the sum (resultant) of the forces must be  $\vec{0}$ .

<sup>a</sup> Carbon 12 has  $\approx 6.02 \times 10^{23}$  molecules. The universe has  $\approx 10^{80}$  molecules.



16.11 ♣ **Free-Body Diagrams for 3D three-balloon system.**

The picture below shows a cup hanging by strings from three motionless helium-filled balloons. Draw **FBDs** of each system for the given assumptions.



Helium is lighter than air.

<u>FBD of cup:</u>	<u>FBD of left string:</u>	<u>FBD of left balloon:</u>
<u>Assumptions in FBD</u> Only relevant forces are Earth’s uniform gravity and contact forces from strings (no wind/air resistance, electromagnetic forces, etc.)	<u>Assumptions in FBD</u> String is inextensible. Only relevant forces are tension in string (gravity/other forces are negligible compared to tension.)	<u>Assumptions in FBD</u> Relevant forces are gravity from Earth, fluid pressure from air (buoyancy), and contact from strings and other balloons.