

12.1 ♣ Two types of forces in a free-body diagram (FBD) (Section 16.5).

From an engineering/FBD perspective, the two types of forces are  and .

12.2 ♣ What is 1 Newton and 1 lbf? (Section 19.1).

|   |  |   |   |  |
|---|--|---|---|--|
| 1 Newton is defined as<br>(circle all that apply)                           | <input type="checkbox"/> $1 \frac{\text{kg m}}{\text{s}^2}$                  | <input type="checkbox"/> $9.81 \frac{\text{kg m}}{\text{s}^2}$                  | <input type="checkbox"/> $32.2 \frac{\text{kg m}}{\text{s}^2}$                  | <input type="checkbox"/> None of these |
| 1 lbf is defined as or<br>approximately equal to<br>(circle all that apply) | <input type="checkbox"/> $1 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$    | <input type="checkbox"/> $1 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$    | <input type="checkbox"/> $1 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$    |  |
|   | <input type="checkbox"/> $9.81 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$ | <input type="checkbox"/> $9.81 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$ | <input type="checkbox"/> $9.81 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$ |  |
|   | <input type="checkbox"/> $32.2 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$ | <input type="checkbox"/> $32.2 \text{ slug} \cdot \frac{\text{ft}}{\text{s}^2}$ | <input type="checkbox"/> $32.2 \text{ lb}_m \cdot \frac{\text{ft}}{\text{s}^2}$ |  |

Using the exact Section 19.1 NIST conversion factor for lbf to kg and the exact conversion factor  $1 \text{ inch} \triangleq 2.54 \text{ cm}$ , show how to calculate the conversion factor for lbf to Newton.

Result

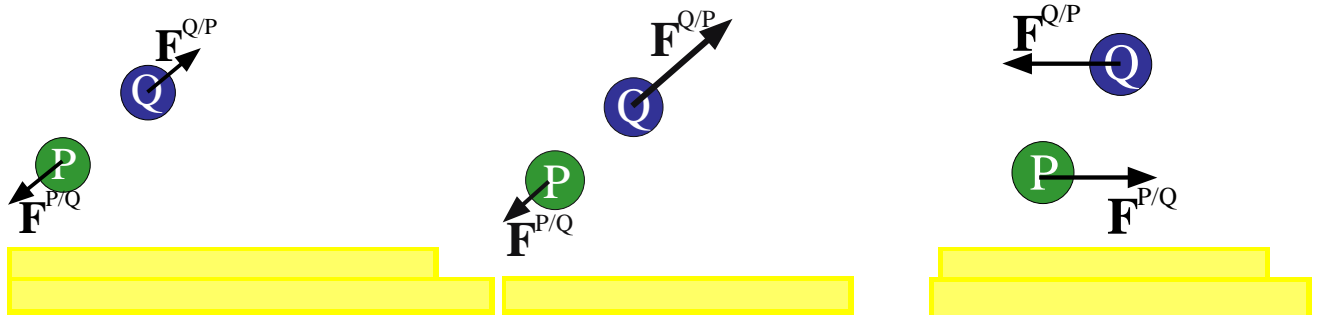
$$1 \text{ lbf} \approx \frac{\text{lb}_m \text{ ft}}{\text{s}^2} * \frac{\text{kg}}{\text{lb}_m} * \frac{\text{inch}}{\text{ft}} * \frac{\text{ft}}{\text{ft}} * \frac{\text{ft}}{\text{ft}} * \frac{\text{N}}{\text{kg m/s}^2} \approx 4.45 \text{ N}$$

12.3 ♣ Force concepts (Section 16.3).

|  |                      |
|--|----------------------|
| A force is a well-defined quantity:  | True/False           |
| The resultant of a set of forces is a force.   | True/False           |
| In the SI (metric) system, the units of force are:   | <input type="text"/> |
| In the SI (metric) system, the units of impulse are:   | <input type="text"/> |
| $\vec{F} = m \vec{a}$ is violated if a non-zero forces exists without the presence of a massive object | True/False           |
| $\vec{F} = m \vec{a}$ is violated if mass exists without the presence of force                         | True/False           |

12.4 ♣ Law of action/reaction (Section 16.1).

Circle the forces that obey the law of action/reaction. Explain why each pair obeys/disobeys.



12.5 ♣ Coulomb's friction law (Section 19.6).

The range for Coulomb's coefficient of static friction is always  $0 \leq \mu_s \leq 1$ . True/False.

Coulomb's friction law is exact/accurate (< 1% error)/approximate/completely wrong.

12.6 ♣ Force and mass concepts (Section 19.1).

|   |            |
|---|------------|
| The center of mass and center of gravity may be different points. | True/False |
| The center of gravity of a rigid body always exists.              | True/False |

**12.7 ♣ Convert U.S. units of psi to SI units of Pascals and estimate stress (Section 19.1).**

Use each conversion factors (number) below at least once (and others you should know) to convert units of 1 inch to **x** meters, 1 lbf (pound-force) to **y** Newtons, and 1 psi ( $\frac{\text{lbf}}{\text{inch}^2}$ ) to **z** Pascals ( $\frac{\text{N}}{\text{m}^2}$ ). Express your results for **z** in terms of the intermediate conversion factors **x** and **y**.

$$1 \text{ inch} \triangleq 2.54 \text{ cm} \qquad 1 \text{ kg} \approx 2.2 \text{ lbm} \qquad 1 \text{ g}_{\text{Earth}} \approx 32.2 \frac{\text{ft}}{\text{s}^2}$$

Conversion Equation (with numbers and units) for calculating result.

|                     |  |   |
|---------------------|--|---|
| 1 in = <b>x</b> m   | <b>x</b> = 1 in * $\frac{2.54 \text{ cm}}{1 \text{ in}}$ * $\frac{1 \text{ m}}{100 \text{ cm}}$ $\approx$ 0.0254                       | <b>Example of how to do units conversions</b> |
| 1 lbf = <b>y</b> N  | <b>y</b> = <span style="background-color: yellow; display: inline-block; width: 150px; height: 1.2em; vertical-align: middle;"></span> | $\approx$ 4.45                                |
| 1 psi = <b>z</b> Pa | <b>z</b> = <span style="background-color: yellow; display: inline-block; width: 150px; height: 1.2em; vertical-align: middle;"></span> | <b>Express z in terms of x and y</b>          |

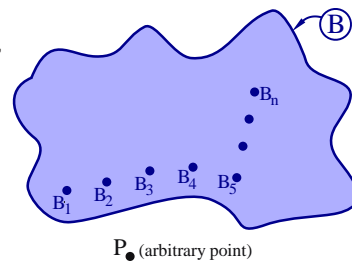
Engineering skill: Estimate/approximate order-of-magnitudes for mass, force, and stress.

|   |                   |         |
|---|-------------------|---------|
| Mass of a laptop computer   | 0.04/0.4/4/40/400 | lbm     |
| Weight of a laptop computer   | 0.04/0.4/4/40/400 | lbf     |
| Weight of a laptop computer   | 0.02/0.2/2/20/200 | Newtons |
| Gage pressure in a bike tire (remember pumping up a bike/car tire?) | 0.05/0.5/5/50/500 | psi     |
| Gage pressure in a bike tire  | 0.03/0.3/3/30/300 | kPa     |
| Stress of a 200 lbf person on one flat sneaker on a wood floor      | 0.05/0.5/5/50/500 | psi     |
| Stress of a 120 lbf person on one stiletto heel on a wood floor     | 0.03/0.3/3/30/300 | psi     |

**12.8 ♣ Forces on an aluminum body (Sections 16.4, 16.2, and 17.4).**

Consider  $6.022 \times 10^{23}$  molecules of aluminum ( $\approx$  27 grams) which define a body *B*. The quantities under investigation (and related moments) are:

- $\vec{F}^B$  the resultant of all forces on *B*
- $\vec{F}_{\text{internal}}^B$  the resultant of all internal forces in *B*
- $\vec{F}_{\text{external}}^B$  the resultant of all external forces on *B*
- $\vec{F}^{B_1/B_2}$  the force on molecule *B*<sub>1</sub> from molecule *B*<sub>2</sub>



| Condition                              | Static equilibrium? | Circle the following statements that are always true. |   |   |                               |
|--|---------------------|---|---|---|-------------------------------|
| <i>B</i> is rigid                      | Yes                 | $\vec{F}^B = \vec{0}$                                 | $\vec{F}_{\text{internal}}^B = \vec{0}$ | $\vec{F}_{\text{external}}^B = \vec{0}$ | $\vec{F}^{B_1/B_2} = \vec{0}$ |
| <i>B</i> is flexible<br>(a thin ruler) | Yes                 | $\vec{F}^B = \vec{0}$                                 | $\vec{F}_{\text{internal}}^B = \vec{0}$ | $\vec{F}_{\text{external}}^B = \vec{0}$ | $\vec{F}^{B_1/B_2} = \vec{0}$ |
| <i>B</i> is rigid                      | No                  | $\vec{F}^B = \vec{0}$                                 | $\vec{F}_{\text{internal}}^B = \vec{0}$ | $\vec{F}_{\text{external}}^B = \vec{0}$ | $\vec{F}^{B_1/B_2} = \vec{0}$ |
| <i>B</i> is molten<br>(liquid metal)   | No                  | $\vec{F}^B = \vec{0}$                                 | $\vec{F}_{\text{internal}}^B = \vec{0}$ | $\vec{F}_{\text{external}}^B = \vec{0}$ | $\vec{F}^{B_1/B_2} = \vec{0}$ |

12.9 ♣ **Measurement accuracies of the Universal Gravitational Constant  $G$**  (Section 19.3).

The gravitational force on a particle  $Q$  of mass  $m^Q$  from a particle  $P$  of mass  $m^P$  can be written in terms of  $Q$ 's position vector from  $P$  as

$$\vec{F}^{Q/P} = \frac{-G m^P m^Q}{|\vec{r}^{Q/P}|^3} \vec{r}^{Q/P} \quad (19.3)$$

What are the dimensions of  $G$  (in terms of mass, length and time) and the SI units of  $G$ ?

**Result:** Dimensions of  $G$ : (in terms of mass, length, time)  Units of  $G$ : (in terms of  $kg, m, s$ )

The number of significant digits the first measurement of the “*Universal Gravitational Constant*”  $G$  in 1798 by Cavendish and recent (year 2000<sup>+</sup>) experiments of  $G$  are estimated to be accurate to:

|                                  |   |   |   |   |          |
|----------------------------------|---|---|---|---|----------|
| Experiments in 1798              | 1 | 2 | 5 | 7 | infinite |
| Experiments in 2000 <sup>+</sup> | 1 | 2 | 5 | 7 | infinite |

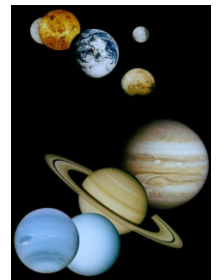
Note: Section 19.3 discusses experiments involving  $G$ .

12.10 ♣ **According to Newton’s laws (theories), is the universe static?** (Sections 16.2 and 17.3)

Consider the system  $S$  consisting of all matter, life, forces, etc.<sup>a</sup>

- Newton’s laws dictates the resultant of all forces on  $S$  is  $\vec{0}$ , i.e.,  $\vec{F}^S = \vec{0}$ . **True/False.**
- The moment of all forces on  $S$  about any point  $P$  is  $\vec{0}$ , i.e.,  $\vec{M}^{S/P} = \vec{0}$ . **True/False.**
- Newton’s laws dictates the universe is in **static equilibrium**. **True/False.**
- Newton’s **1<sup>st</sup>/2<sup>nd</sup>/3<sup>rd</sup>** law explains my answer? (circle one)

Why:



<sup>a</sup>Carbon 12 has  $\approx 6.02 \times 10^{23}$  molecules. The universe has  $\approx 10^{80}$  molecules.

12.11 ♣ **Free-Body Diagrams for 3D three-balloon system.**

The picture below shows a cup hanging by strings from three motionless helium-filled balloons. Draw **FBDs** of each system for the given assumptions.



Helium is lighter than air.

|  |  |   |
|--|--|---|
| <p><u>FBD of cup:</u></p>  | <p><u>FBD of left string:</u></p>  | <p><u>FBD of left balloon:</u></p>  |
| <p><b><u>Assumptions in FBD</u></b><br/>                 Only relevant forces are Earth’s uniform gravity and contact forces from strings (no wind/air resistance, electromagnetic forces, etc.)</p> | <p><b><u>Assumptions in FBD</u></b><br/>                 String is inextensible. Only relevant forces are tension in string (gravity/other forces are negligible compared to tension.)</p> | <p><b><u>Assumptions in FBD</u></b><br/>                 Relevant forces are gravity from Earth, fluid pressure from air (buoyancy), and contact from strings and other balloons.</p> |