

Show work – except for ♣ fill-in-blanks (print .pdf from [www.MotionGenesis.com](http://www.MotionGenesis.com) ⇒ [Textbooks](#) ⇒ [Resources](#)).

## 12.1 ♣ Matrix rows and columns

$$\begin{aligned} \text{Given: } M &= \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} & \text{Row 1 of } M &= \begin{bmatrix} 1 & 2 \end{bmatrix} & \text{Row 2 of } M &= \begin{bmatrix} 3 & 4 \end{bmatrix} \\ M_{2,1} &= 3 & \text{Column 1 of } M &= \begin{bmatrix} 1 \\ 3 \end{bmatrix} & \text{Column 2 of } M &= \begin{bmatrix} 2 \\ 4 \end{bmatrix} \end{aligned}$$

## 12.2 ♣ Matrix transpose

$$\text{Transpose} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \quad \text{Transpose} \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a & d \\ b & e \\ c & f \end{bmatrix}$$

## 12.3 ♣ Matrix addition and subtraction (+, -)

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} = \begin{bmatrix} 6 & 8 \\ 10 & 12 \end{bmatrix} \quad \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} - \begin{bmatrix} 2 & 4 & 6 \\ 3 & 5 & 7 \end{bmatrix} = \begin{bmatrix} a-2 & b-4 & c-6 \\ d-3 & e-5 & f-7 \end{bmatrix}$$

## 12.4 ♣ Scalar-matrix multiplication (\*)

$$5 * \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 5 & 10 \\ 15 & 20 \end{bmatrix} \quad 5 * \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} 5a & 5b & 5c \\ 5d & 5e & 5f \end{bmatrix}$$

## 12.5 ♣ Matrix-matrix multiplication (\*)

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 3a + 5b \\ 3c + 5d \end{bmatrix} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{bmatrix} 3 & x \\ 5 & y \end{bmatrix} = \begin{bmatrix} 3a + 5b & ax + by \\ 3c + 5d & cx + dy \end{bmatrix}$$

$$\begin{bmatrix} a \\ b \end{bmatrix} * \begin{bmatrix} x & y \end{bmatrix} = \begin{bmatrix} ax & ay \\ bx & by \end{bmatrix} \quad \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} * \begin{bmatrix} x & 3 \\ y & 5 \\ z & 7 \end{bmatrix} = \begin{bmatrix} ax + by + cz & 3a + 5b + 7c \\ dx + ey + fz & 3d + 5e + 7f \end{bmatrix}$$

## 12.6 ♣ Matrix determinants

$$\det [5] \triangleq 5 \quad \det \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = 1 * 4 - 2 * 3 = -2 \quad \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ab - cd$$

$$\det [a] \triangleq a$$

Calculate the following determinant three ways: expand along the 1<sup>st</sup> row, 1<sup>st</sup> column, 2<sup>nd</sup> row.

$$\begin{aligned} \det \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 0 & 9 \end{bmatrix} &= +1 \det \begin{bmatrix} 5 & 6 \\ 0 & 9 \end{bmatrix} + -2 \det \begin{bmatrix} 4 & 6 \\ 7 & 9 \end{bmatrix} + +3 \det \begin{bmatrix} 4 & 5 \\ 7 & 0 \end{bmatrix} &= -48 \\ &= +1 \det \begin{bmatrix} 5 & 6 \\ 0 & 9 \end{bmatrix} + -4 \det \begin{bmatrix} 2 & 3 \\ 0 & 9 \end{bmatrix} + +7 \det \begin{bmatrix} 2 & 3 \\ 5 & 6 \end{bmatrix} &= -48 \\ &= -4 \det \begin{bmatrix} 2 & 3 \\ 0 & 9 \end{bmatrix} + +5 \det \begin{bmatrix} 1 & 3 \\ 7 & 9 \end{bmatrix} + -6 \det \begin{bmatrix} 1 & 2 \\ 7 & 0 \end{bmatrix} &= -48 \end{aligned}$$

Calculate the determinant by expanding along the 3<sup>rd</sup> column.

$$\det \begin{bmatrix} a & b & c \\ d & e & 0 \\ g & h & 0 \end{bmatrix} = +c * \det \begin{bmatrix} d & e \\ g & h \end{bmatrix} = c(dh - eg)$$

### 12.7 ♣ Matrix form of scalar equations (matrix multiplication in reverse)

Put the following sets of scalar equations into matrix form.

$\begin{aligned} ax + by &= 12 \\ dx + ey &= 15 \end{aligned}$ $\begin{bmatrix} a & b \\ d & e \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 12 \\ 15 \end{bmatrix}$	$\begin{aligned} ax + by + cz &= 12 \\ dx + ey + fz &= 15 \end{aligned}$ $\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 12 \\ 15 \end{bmatrix}$	$\begin{aligned} ax + by - 12 &= 0 \\ dx + ey - 15 &= 0 \end{aligned}$ $\begin{bmatrix} x & y & 0 & 0 \\ 0 & 0 & x & y \end{bmatrix} \begin{bmatrix} a \\ b \\ d \\ e \end{bmatrix} = \begin{bmatrix} 12 \\ 15 \end{bmatrix}$
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### 12.8 Optional: Solving sets of linear algebraic equations.

$$\begin{aligned} ax + by &= 1 \\ dx + ey &= 2 \end{aligned}$$

Solve for  $x, y$ .

$$x = \frac{e - 2b}{ae - bd} \quad y = \frac{2a - d}{ae - bd}$$

$$\begin{aligned} ax + by + cz &= 1 \\ 2x + 3y + 4z &= 2 \\ 2x + 4y + 6z &= 4 \end{aligned}$$

Solve for  $x, y, z$ .

$$x = \frac{-1 - 2b + 2c}{2b - a - c} \quad y = \frac{2 + 2a - 2c}{2b - a - c} \quad z = \frac{-1 - 2a + 2b}{2b - a - c}$$

### 12.9 Concepts: Eigenvalues and eigenvectors

Do all the questions in Section 22.2.

### 12.10 ♣ Eigenvalues, determinants, and matrix algebra

- One test that the inverse of the  $n \times n$  matrix  $A$  does *not* exist is  $\det(A) = 0$
- The eigenvalues of the matrix  $A$  can be determined by setting  $\det(-\lambda I + A) = 0$
- If an eigenvalue of the matrix  $A$  is zero,  $A^{-1}$  does *not* exist. True/False.

### 12.11 ♣ Concepts: Eigenvalues and eigenvectors

Consider the following set of algebraic equations governing the unknowns  $u_1, u_2$ , and  $\lambda$ .

$$\begin{aligned} \lambda u_1 - u_2 &= 0 \\ 25u_1 + (\lambda - 6)u_2 &= 0 \end{aligned} \quad \text{or equivalently} \quad \begin{bmatrix} \lambda & -1 \\ 25 & \lambda - 6 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Find “special values” of  $\lambda$  (called *eigenvalues*) that allow for  $\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

**Result:**  $\lambda_1 = 3 + 4i$   $\lambda_2 = 3 - 4i$

For each special value of  $\lambda$  determine a corresponding “special ratio” of  $u_2$  to  $u_1$ .

**Result:** (These “special ratios” are called *eigenvectors* and  $c_1$  and  $c_2$  are arbitrary constants.)

$$\text{For } \lambda_1: U_1 \triangleq \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 3 + 4i \end{bmatrix} \quad \text{For } \lambda_2: U_2 \triangleq \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = c_2 \begin{bmatrix} 1 \\ 3 - 4i \end{bmatrix}$$

### 12.12 ♣ Optional: Matrix inverse with determinants and adjugate (adjunct) matrices

Calculate the following matrix inverses (the  $3 \times 3$  matrix inverses are optional).

$$\text{inv}[5] = \frac{\text{adj}[5]}{\det[5]} = \frac{[1]}{5} = [0.2] \quad \text{inv}[a] = \begin{bmatrix} 1 \\ a \end{bmatrix}$$

$$\text{inv} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \frac{\text{adj} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}}{\det \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}} = \frac{\begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}}{-2} = \begin{bmatrix} -2 & 1 \\ 1.5 & -0.5 \end{bmatrix}$$

$$\text{inv} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \frac{\text{adj} \begin{bmatrix} a & b \\ c & d \end{bmatrix}}{\det \begin{bmatrix} a & b \\ c & d \end{bmatrix}} = \frac{\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}}{ad - bc}$$

$$\text{inv} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 0 & 9 \end{bmatrix} = \begin{bmatrix} -0.9375 & 0.375 & 0.0625 \\ -0.125 & 0.25 & -0.125 \\ 0.7291667 & -0.2916667 & 0.0625 \end{bmatrix}$$

$$\text{inv} \begin{bmatrix} a & b & c \\ d & e & 0 \\ g & h & 0 \end{bmatrix} = \begin{bmatrix} 0 & h/(d*h - e*g) & -e/(d*h - e*g) \\ 0 & -g/(d*h - e*g) & d/(d*h - e*g) \\ 1/c & -(a*h - b*g)/(c*(d*h - e*g)) & (a*e - b*d)/(c*(d*h - e*g)) \end{bmatrix}$$

### 12.13 Optional: Matrix computation with MotionGenesis and/or MATLAB®

Use MotionGenesis or MATLAB® to do Hw 12.1 - 12.8 (skip Hw 12.7). For example, print and submit a MotionGenesis command file named `MatrixAlgebra.txt` that uses the following commands.

GetElement	GetRow	GetColumn	GetTranspose
+ - *	GetDeterminant	GetInverse	Solve